

ENX 8 MAG Encoder Ø8 mm, 1...256 CPT

ENX



Key Data		ENX 8 MAG Incremental	ENX 8 MAG Incremental, Commutation Signal
Number of channels	3	3	3
Max. counts per turn	256	256	256
Additional length at motor	mm 7.0	1.0	1.0
Ambient temperature	°C -40...100	-40...100	-40...100
Weight	g 1	1	1

Selection criteria		ENX 8 MAG Incremental	ENX 8 MAG Incremental, Commutation Signal
Speed and rotation direction detection		■	■
Speed and position control		■	■
Compact and robust design		■	■
High resolution		▲	▲
Cost effective		■	■

■ suitable ▲ suitable to a limited extent ● not suitable

Specifications		ENX 8 MAG Incremental	ENX 8 MAG Incremental, Commutation Signal
Supply voltage Vcc	V	3.0...3.6	3.0...3.6
Typical current draw	mA	13	13
Max. operating frequency	kHz	500	500
Max. Speed	rpm	100 000	100 000
Connection ³		FPC, 12 pole, pitch 0.5 mm Pin 1 Motor+ Pin 2 Motor- Pin 3 Not connected Pin 4 GND Pin 5 V _{cc} Pin 6 Channel A Pin 7 Channel B Pin 8 Channel I Pin 9-12 Do not connect ¹ Output signal: CMOS compatible Output current per channel: ±4 mA	FPC, 12 pole, pitch 0.5 mm Pin 1 W1 Pin 2 W2 Pin 3 W3 Pin 4 GND Pin 5 V _{cc} Pin 6 Channel A Pin 7 Channel B Pin 8 Channel I Pin 9 H1 Pin 10 H2 Pin 11 H3 Pin 12 Do not connect ¹ Output signal: CMOS compatible Output current per channel: ±4 mA

Configuration		ENX 8 MAG Incremental	ENX 8 MAG Incremental, Commutation Signal
Counts per turn ²		1...256	1...256

maxon Modular System	Page	Dimensions Standard Version	Notes
maxon DC motor			
DCX 8 M	86		¹ Applying voltage to these pins may destroy the encoder.
maxon EC motor			² maxon controllers require a resolution of at least 16 pulses.
ECX SPEED 8 M	185-186		³ H1, index and angle zero are aligned with angle commutation zero (see p. 56).
			Compatible connector: Molex 52745-1297, TE 1-1734839-2 Adapter 498157 required for all maxon controllers
			Please note: max. continuous current 0.5 A

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